

FACTORY AUTOMATION

# Mitsubishi Electric Servo System Family Catalog

Leading the World with the industry's Top Class Technology

# <section-header>

# GLOBAL IMPACT OF MITSUBISHI ELECTRIC



Through Mitsubishi Electric's vision, "Changes for the Better" are possible for a brighter future.

# Changes for the Better

We bring together the best minds to create the best technologies. At Mitsubishi Electric, we understand that technology is the driving force of change in our lives. By bringing greater comfort to daily life, maximizing the efficiency of businesses and keeping things running across society, we integrate technology and innovation to bring changes for the better. Mitsubishi Electric is involved in many areas including the following

### **Energy and Electric Systems**

A wide range of power and electrical products from generators to large-scale displays.

### **Electronic Devices**

A wide portfolio of cutting-edge semiconductor devices for systems and products.

### **Home Appliance**

Dependable consumer products like air conditioners and home entertainment systems.

# Information and Communication Systems

Commercial and consumer-centric equipment, products and systems.

### **Industrial Automation Systems**

Maximizing productivity and efficiency with cutting-edge automation technology.

# **OVERVIEW**

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# **Related Catalogs**

# Refer to the following catalogs for details:



Mitsubishi Electric Servo System Controllers MELSEC iQ-R/MELSEC iQ-F series catalog L(NA)03100



Mitsubishi Electric General-Purpose AC Servo MELSERVO-J4 catalog L(NA)03058



MELSEC iQ-R Series iQ Platform-compatible PAC catalog L(NA)08298ENG



MELSEC iQ-F Series catalog L(NA)08428ENG



Ethernet-based Open Network CC-Link IE Product Catalog L(NA)08111E

# **Servo Application Examples**

Industry leading performance MELSERVO supports various system configurations.

Going beyond servo amplifiers and servo motors, Mitsubishi Electric offers system level solutions that include programmable controllers, Motion controllers, and networks to satisfy a broad scope of needs.

# Automotive manufacturing



# **Material handling**



Improve productivity and realize flexibility in different automotive assembly lines with high-accuracy motion control, including linear/circular interpolation and electric cam profile.

Realize advanced logistics coordination and eliminate errors in repetitive processes. Servo-based high-speed material handling and highly accurate positioning improve productivity and reduce energy consumption.

## Food processing machines



Realize improvements in various packaging applications such as high-speed filling, which requires a highly accurate, continuous feed rate and precision.

## Semiconductor manufacturing equipment



In today's semiconductor manufacturing process, wafer diameter is getting larger and components smaller. To meet the requirements of higher quality and productivity, Mitsubishi Electric's high-performance servos and high-resolution encoder achieve fast and accurate positioning at stable speeds.

# Mounters



# FPD manufacturing systems



Flexible mounting of electronic components with high speed and density is demanded in printed circuit board applications. Mitsubishi Electric offers a high level of servo system solutions for rapid mounting of highly miniaturized components and for flexible mounting of irregular shapes.

In addition to the high-speed and high-accuracy positioning control, linear servos and a broad array of other actuators play important roles in the manufacturing of constantly evolving flat panel displays.

Mitsubishi Electric provides high-accuracy synchronous system solutions for the paper feeding, printing, cutting, and assembly functions within the printing process, achieving high-speed and high-quality

converting applications.

**Printing machines** 



**Injection molding machines** 



The integrated system with the advanced motion control supports high-accuracy

molding in injection molding machines, which consist of various control sections.

**Machine tools** 



High-performance servos enable fast and accurate positioning, and support high-speed handling of works. We promote the sophisticated machining capabilities that are a key part of the world's most advanced manufacturing.

# Mitsubishi Electric Servo System

# **Our Total Solution for Your Satisfaction**

As the leading supplier of automation products and solutions worldwide, Mitsubishi Electric, known for its high quality and diverse range of automation products including servo system controllers, servo amplifiers, and servo motors, together with our exclusive engineering software and various networks including "CC-Link IE Field Network" and "SSCNET III/H", boasts a whole range of solutions specific to your needs.

| Controllers                         |  | Progra  | ammable controlle  | er                                   |  |
|-------------------------------------|--|---|--|--------------------------------------|--|
|                                     | MELSEC IQ-R series   | MELSEC-Q series M   | ELSEC-L series   | MELSEC iQ-F series ME                | ELSEC-F series   |
| - All                               | Master/local module  | S<br>Field Network  | imple Motion mod   | lule<br>SCNET III/H                  | C controller<br>interface module<br>SSCNET III/H                           |
|                                     |  |   |  | <b>1</b>                             | J  |
| 22                                  | RJ71GF11-T2<br>QJ71GF11-T2   | RD77GF<br>QD77GF  | RD77MS<br>QD77MS   | LD77MS FX5-40SSC-S<br>FX5-80SSC-S    | Q173SCCF   |
| Interface                           | CC-Link IE<br>Field Network  | CC-Link IE<br>Field Network Basic                                   |  | SSCNET III/H                         |  |
|                                     | CC-Línk <b>IE</b> Eield<br>CC-Línk <b>IE</b> Eield Basic                               | CC-Línk IE Elield Basic   |  |                                      |  |
| Servo Amplifiers<br>Sensing Modules | MR-J4-GF<br>CC-Link IE Field<br>Network compatible<br>servo amplifier<br>MR-J4-GF(-RJ) | MR-JE-C<br>NEW<br>Ethernet compatible<br>servo amplifier<br>MR-JE-C | SSCNET III/H<br>compatible<br>servo amplifier<br>MR-J4-B(-R  | compatible<br>2-axis servo amplifier | 4W3-B<br>SSCNET III/H<br>compatible<br>3-axis servo amplifier<br>MR-J4W3-B |
|                                     |  | * MR-JE-C also supports the<br>pulse train input.                   | 9  |                                      |  |
| Servo Motors                        | Small cap<br>low inertia<br>HG-KR<br>Capacity: 5                                       | series  | ervo motor for MF<br>Small capacity,<br>ultra-low inertia<br>HG-MR series<br>Capacity: 50 to 750 V | Mec<br>med<br>HG                     | lium capacity,<br>lium inertia<br><b>-SR series</b><br>acity: 0.5 to 7 kW  |
|                                     | Medium/la<br>low inertia<br>HG-JR &<br>Capacity: 0                                     | series  | Ultra-compact,<br>ultra-small capaci<br>HG-AK series<br>Capacity: 10 to 30 W                       | ity ultra                            | lium capacity,<br>L-low inertia<br><b>-RR series</b><br>acity: 1 to 5 kW   |
|                                     | Medium c<br>flat type<br>HG-UR<br>Capacity: 0  | series  | Ultra-large<br>capacity,<br><b>HG-JR series</b><br>Capacity: 110 to 220                            | in the future Larg                   | je capacity,<br>i-low inertia<br><b>-RR series</b><br>acity: 11 to 22 kW   |

Solution e-F@ctory is the Mitsubishi Electric solution for improving the performance of any e-F@ctory manufacturing enterprise by enhancing productivity, and reducing the maintenance and operation costs together with seamless information flow throughout the plant. Mitsubishi Electric's integrated FA platform for achieving lateral integration of **1U** Platform controllers &HMI, engineering environments and networks at production sites.





Rating: 2.2 to 9 N·m

Core type with magnetic attraction counter-force LM-K2 series Rating: 120 to 2400 N

Coreless type LM-U2 series Rating: 50 to 800 N TM-RU2M series Rating : 2.2 to 9 N

TM-RFM series Rating: 2 to 240 N

Medium capacity, medium inertia

> **HG-SN** series Capacity: 0.5 to 3 kW

# Controllers

# From simple positioning to multi-axis and high-speed systems

Our extensive product lines cover from Positioning modules, which enables positioning with simple programs, to Simple Motion modules and Motion controllers, which enable advanced control.

# **MELSEC iQ-R series**

The MELSEC iQ-R series is equipped with the new, high-speed system bus, achieving a shorter cycle time.

## Simple Motion module

# RD77GF



The RD77GF is a CC-Link IE Field Network compatible Simple Motion module which combines the versatility of Ethernet and highly accurate synchronous operation for Motion control.

The module easily performs various control, such as synchronous, cam, and speed-torque control using only sequence programs.

|                        | RD77GF4                  | RD77GF8      | RD77GF16      | RD77GF32      |
|------------------------|--------------------------|--------------|---------------|---------------|
| Number of control axes | Up to 4 axes             | Up to 8 axes | Up to 16 axes | Up to 32 axes |
| Operation cycle        | 0.5 ms or longer         |              |               |               |
| Servo amplifier        | MR-J4-GF(-RJ)            |              |               |               |
| Command interface      | CC-Link IE Field Network |              |               |               |

# Simple Motion module

### RD77MS



# **Motion controller**

### **RnMTCPU**



The RD77MS is an intelligent function module which easily performs various control, such as positioning, synchronous, cam, and speed-torque (tightening & press-fit) control using only sequence programs.

|                        | RD77MS2                         | RD77MS4      | RD77MS8      | RD77MS16      |
|------------------------|---------------------------------|--------------|--------------|---------------|
| Number of control axes | Up to 2 axes                    | Up to 4 axes | Up to 8 axes | Up to 16 axes |
| Operation cycle        | 0.444 ms or longer              |              |              |               |
| Servo amplifier        | MR-J4-B(-RJ)/MR-J4WB<br>MR-JE-B |              |              |               |
| Command interface      | SSCNET III/H                    |              |              |               |

SSCNETIII/H

SSCNET III/H

MELSEC iQ R

CC-Línk

The RnMTCPU is a CPU module which performs control using the Motion SFC program, independently of a PLC CPU.

The controller performs various advanced Motion control, such as positioning, speed, torque, tightening & press-fit, synchronous, and cam control.

Add-on libraries can be additionally installed to the Motion controller to expand its functionality. With "G-code control add-on library" (not free of charge), the Motion controller can use G-code programs to control a processing machine using general-purpose AC servo. With an add-on library "machine library" (free of charge), the controller can control a simplified robot (link configuration).

|                        | R16MTCPU             | R32MTCPU      | R64MTCPU      |
|------------------------|----------------------|---------------|---------------|
| Number of control axes | Up to 16 axes        | Up to 32 axes | Up to 64 axes |
| Operation cycle        | 0.222 ms or longer   |               |               |
| Servo amplifier        | MR-J4-B(-RJ)/MR-J4WB |               |               |
| Command interface      | SSCNET III/H         |               |               |

# **Positioning module**

# RD75P/RD75D



The RD75P/RD75D are capable of controlling up to four axes with a high-speed pulse output (5 Mpulses/s<sup>-1</sup> at fastest). The RD75P and the RD75D are compatible with the transistor output and the differential driver output respectively.

\*1. This speed is applicable when a differential driver output type is used. The speed depends on the specifications of servo amplifiers

|                        | RD75P2   | RD75P4       | RD75D2               | RD75D4                |
|------------------------|--|--------------|----------------------|-----------------------|
| Number of control axes | Up to 2 axes                                   | Up to 4 axes | Up to 2 axes         | Up to 4 axes          |
| Start time             | 0.3 ms or longer                               |              |                      |                       |
| Servo amplifier        | MR-J4-A(-RJ)<br>MR-JE-A/MR-JE-C                |              |                      |                       |
| Command interface      | Pulse train (transistor output) Pulse train (d |              | Pulse train (differe | ential driver output) |

# **MELSEC-Q** series

A variety of MELSEC-Q series controllers fully meets the control needs in each industry and field.

# **Simple Motion module**

# QD77GF

The QD77GF is a CC-Link IE Field Network compatible Simple Motion module which combines the versatility of Ethernet and highly accurate synchronous operation for Motion control. QD77GF4: 4 axes QD77GF8: 8 axes QD77GF16: 16 axes



CC-Línk IE Field

# Simple Motion module

# QD77MS

The QD77MS is simple to use just like Positioning modules while capable of performing various control, such as positioning, synchronous, cam, and speed-torque control (tightening & press-fit) using only sequence 2 axes 4 axes QD77MS16: 16 axes

MELSEC O series

SSCNET III/H

SSCNET III/H

# **Motion controller**

# Q17nDSCPU

The Q17nDSCPU is a CPU module used with a PLC CPU for Motion control. Q172DSCPU: 16 axes Q173DSCPU: 32 axes



SSCNET III/H

# **Positioning module**

### QD75PN/QD75DN

The QD75PN/QD75DN are pulse train output compatible modules. The QD75PN is for transistor output, and the QD75DN is for differential driver output. QD75P1N/QD75D1N: 1 axis

QD75P2N/QD75D2N: 2 axes QD75P4N/QD75D4N: 4 axes



programs. QD77MS2: QD77MS4:

Stand-alone Motion controller

# Q170MSCPU

The Q170MSCPU is an all-in-one controller integrating a power supply, a PLC, and a Motion controller. Q170MSCPU: 16 axes (Equivalent to Q03UDCPU) Q170MSCPU-S1: 16 axes (Equivalent to Q06UDHCPU)



# Positioning module

### QD70P/QD70D

The QD70P/QD70D are pulse train output compatible modules. These modules are suitable for driving stepping motors because they enable smooth acceleration/deceleration with gradual speed change. QD70P4/QD70D4: 4 axes QD70P8/QD70D8: 8 axes



# **MELSEC iQ-F series**

# MELSEC iQ-F

SSCNET III/H

From stand-alone use to networked system applications, the MELSEC iQ-F series brings your business to the next level of industry.

# Simple Motion module

FX5-40SSC-S/FX5-80SSC-S



The FX5-40SSC-S/FX5-80SSC-S are next-generation, compact servo system controllers with extensive built-in functions.

These modules easily perform various control, such as synchronous, cam, and speed-torque control (tightening & press-fit) using only sequence programs.

|                        | FX5-40SSC-S                     | FX5-80SSC-S  |  |
|------------------------|---------------------------------|--------------|--|
| Number of control axes | Up to 4 axes                    | Up to 8 axes |  |
| Servo amplifier        | MR-J4-B(-RJ)/MR-J4WB<br>MR-JE-B |              |  |
| Command Interface      | SSCNE                           | ET III/H     |  |

# PLC CPU module (built-in positioning function)

### FX5U/FX5UC series



The FX5U/FX5UC feature a built-in positioning function with 4-axis pulse output. They can execute positioning by using a positioning instruction and table operation. Together with high-speed pulse I/O modules, control of up to 12 axes is possible.

|                        | FX5U/FX5UC series                  |                                |  |
|------------------------|------------------------------------|--------------------------------|--|
| Number of control axes | Up to 4 axes                       |                                |  |
| Servo amplifier        | MR-J4-A(-RJ)<br>MR-JE-C<br>MR-JE-A | MR-J4-GF(-RJ)<br>MR-JE-C       |  |
| Command Interface      | Pulse train (transistor output)    | CC-Link IE Field Network Basic |  |

# **MELSEC-L** series

The MELSEC-L series is a baseless highly scalable controller ideal for applications having limited space.

SSCNET III/H

# Simple Motion module

## LD77MS

The LD77MS is simple to use just like Positioning modules while capable of performing various control, such as positioning, synchronous, cam, and speed-torque (tightening & press-fit) control. LD77MS2: 2 axes LD77MS4: 4 axes LD77MS16: 16 axes



# SSCNET III/H Head module



MELSEG L series

The SSCNET III/H head module is used to connect the MELSEC-L series I/O module and the intelligent function module to SSCNET III/H.



# **Positioning module**

# LD75P/LD75D

The LD75P/LD75D are pulse train output compatible modules. The LD75P is for transistor output, and the LD75D is for differential driver output. LD75P1/LD75D1: 1 axis

LD75P2/LD75D2: 2 axes LD75P4/LD75D4: 4 axes



# PLC CPU module (built-in positioning function)

# LCPU

LJ72MS15

The positioning function, equipped as standard, outputs command pulses to a servo amplifier by using the built-in I/O function.

Control axes: 2 axes



# **MELSEC-F** series

# Main unit (built-in positioning function)

### FX3U/FX3UC

The FX30 and FX30c feature positioning functionality with pulse outputs, enabling positioning control only with the main unit. EXau and EXauct 3 axes



### FX<sub>3U</sub>

# Positioning module

# FX3U-1PG

This pulse train output block is used with the FX series programmable controller FX3U-1PG: 1 axis



FX3U-1PG

# Ethernet-based open network CC-Link IE master stations

CC-Línk

Servo control is enabled by the Ethernet-based open network CC-Link IE compatible master station. The following are examples of master stations.

# Master/local module

# RJ71GF11-T2/QJ71GF11-T2

The RJ71GF11-T2/QJ71GF11-T2 are master/local modules supporting CC-Link IE Field Network. With these modules, MR-J4-GF(-RJ) can be used in I/O mode for positioning control

RnENCPU and L series master/local

module can also be used as a master



# **CPU** module

# FX5U/FX5UC/RnCPU/RnENCPU

The FX5U/FX5UC/RnCPU/RnENCPU are PLC CPU modules supporting CC-Link IE Field Network Basic. Having a built-in Ethernet port, these CPU modules can be used as a master station.

The equivalent CPU modules are also available in Q and L series.



FX5U

station.

# C Controller/Personal computer embedded type servo system controllers

A combination of the board controllers and a personal computer, or the interface module and a C controller enables high-response servo control.

# Simple Motion board

### MR-EM340GF

Embedded in a personal computer, the MR-EM340GF Simple Motion board controls MR-J4-GF through a user program.

The controller supports PCI Express®. Control axes in motion mode: 16 axes Control stations in I/O mode: 120 stations

# C Controller Interface Module

### Q173SCCF

Connected directly to a C Controller via PCI Express®, the Q173SCCF controls MR-J4-B through a user program. Q173SCCF: 20 axes



# **Position Board**



# **MR-MC** series

Embedded in a personal computer, the MR-MC series Position Boards control MR-J4-B through a user program. The controllers support PCI Express®, PCI bus, and Compact PCI®. MR-MC2\_0: 20 axes MR-MC2 1: 32 axes MR-MC341: 64 axes







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Controllers

# MELSEC-





CC-Línk IE Field

# Servo Amplifiers

From the industry's top level high-speed, high-accuracy servos to one-touch servos and multi-axis models. In addition to the high-end MELSERVO-J4 series, a variety of models to match various applications is available. The Mitsubishi Electric's servo amplifiers support motors from rotary servo motors to linear servo motors and direct drive motors, and greatly enhance system performance.

# ~Man, Machine and Environment in Perfect Harmony~

# **MELSERVO-J4** series

MELSERVO-J4 series is the leading member of the MELSERVO family, backed by Mitsubishi Electric's leadership in all-digital technology. With safety, Ethernet-based CC-Link IE Field Network, SSCNET III/H high-speed optical communication and energy-efficient design of the MELSERVO-J4 series - man, machine and environment can at last work together in perfect harmony.

MR-J4-GF(-RJ) **CC-Link IE Field** Network compatible servo amplifier

CC-Línk CC-Línk IE Field Basic



This servo amplifier is compatible with CC-Link IE Field Network. Together with the Simple Motion module, advanced synchronous control and interpolation control by sequential commands are enabled. The servo amplifier has a built-in point table function (point table method/indexer method), offering easy positioning with a combination with a master module. The servo amplifier also supports CC-Link IE Field Network Basic.

| Command interface      | CC-Link IE Field Network                         |          |          |
|------------------------|--|----------|----------|
| Control mode           | Position/Speed/Torque/Fully closed loop          |          |          |
| Power supply           | 100 V AC   | 200 V AC | 400 V AC |
| Capacity range         | 0.1 kW to 0.4 kW 0.1 kW to 22 kW 0.6 kW to 22 kW |          |          |
| Compatible servo motor | Rotary servo motor, linear servo motor, DD motor |          |          |

MR-J4-B(-RJ) MR-J4W2-B/MR-J4W3-B



SSCNET III/H compatible servo amplifier



MR-J4-A(-RJ) General-purpose interface compatible servo amplifier







| Command interface      |  | SSCNET III/H               |  |  |
|------------------------|--|----------------------------|--|--|
| Control mode           | Position/Speed/Torque/Fully closed loop          |                            |  |  |
| Power supply           | 100 V AC   | 100 V AC 200 V AC 400 V AC |  |  |
| Capacity range         | 0.1 kW to 0.4 kW 0.1 kW to 37 kW 0.6 kW to 55 kW |                            |  |  |
| Compatible servo motor | Rotary servo motor, linear servo motor, DD motor |                            |  |  |

Pulse train and analog input, etc., are provided as a standard for the command interface. Position, speed, and torque control modes are available, and the modes can be switched with an input device.

The MR-J4-A-RJ has a built-in positioning function, supporting MODBUS® RTU, simple cam, and mark sensor input compensation.

| Command interface      | Pulse train/Analog voltage/RS-422/MODBUS® RTU    |                 |                 |
|------------------------|--|-----------------|-----------------|
| Control mode           | Position/Speed/Torque/Fully closed loop          |                 |                 |
| Power supply           | 100 V AC   | 200 V AC        | 400 V AC        |
| Capacity range         | 0.1 kW to 0.4 kW                                 | 0.1 kW to 37 kW | 0.6 kW to 55 kW |
| Compatible servo motor | Rotary servo motor, linear servo motor, DD motor |                 |                 |

This servo amplifier is compatible with the ultra-compact HG-AK servo motor series (10 W to 30 W) and two types of main circuit power supply of 48 V DC and 24 V DC, being suitable for compact machines. 2-axis servo amplifiers are also available.

| Command interface      | SSCNET III/H or Pulse train/Analog voltage/RS-422 |
|------------------------|---|
| Control mode           | Position/Speed/Torque                             |
| Power supply           | 48 V DC/24 V DC                                   |
| Capacity range         | 10 W to 30 W                                      |
| Compatible servo motor | Rotary servo motor                                |

# Harmony with Machine

The leading edge in drive control, with unrivaled accuracy and response for next-generation machine performance.

# Industry-Leading Level of Servo Amplifier Basic Performance

Speed frequency response of 2.5 kHz is achieved by applying our original high-speed servo control architecture evolved from the conventional two-degrees-of-freedom model adaptive control to the dedicated execution engine. Together with a high-resolution absolute position encoder of 4,194,304 pulses/rev, fast and accurate operation is enabled. The performance of the high-end machines is utilized to the fullest.







# **One-Touch Tuning**

Just turn on the one-touch tuning function to complete servo gain adjustment automatically, including machine resonance suppression filter, advanced vibration suppression control II<sup>-1</sup>, and robust filter for maximizing your machine performance. This function also sets responsivity automatically, while the real-time auto tuning requires manual setting. Moreover, a new method<sup>-2</sup> allows to create an optimum tuning command inside the servo amplifier.



\*1. The advanced vibration suppression control II automatically adjusts one frequency. \*2. This new method is supported by MR-J4-B/MR-J4W\_-B/MR-J4-A.

# Advanced Vibration Suppression Control II

The advanced vibration suppression control II suppresses two types of low-frequency vibrations, owing to vibration suppression algorithm which supports three-inertia system. This function is effective in suppressing residual vibration with relatively low frequency of approximately 100 Hz or less generated at the end of an arm and in a machine, enabling a shorter settling time.



# **Robust Filter**

Achieving both high responsivity and stability was difficult with the conventional control in high-inertia systems with belts and gears such as printing and packaging machines. Now, this function enables the high responsivity and the stability at the same time without adjustment. The robust filter gradually reduces the fluctuation of torque in a wide frequency range and achieves more stability as compared to the prior model.



# **Expanded Machine Resonance Suppression Filter**

With advanced filter structure, applicable frequency range is expanded from between 100 Hz and 4500 Hz to between 10 Hz and 4500 Hz. Additionally, the number of simultaneously applicable filters is increased from two to five, improving vibration suppression performance of a machine.



# **Lost Motion Compensation Function**

This function suppresses quadrant protrusion caused by friction and torsion generated when the servo motor rotates in a reverse direction. Therefore, the accuracy of circular path will be improved in trajectory control used in XY table, etc.

\* This function is not supported by MR-J4W2-B and MR-J4W3-B.



Suppression of quadrant protrusion of circular trajectory

# **Built-in Positioning Function**

MR-J4-GF(-RJ) and MR-J4-A-RJ have a built-in positioning function, enabling positioning operation with point table, program-based\*, and indexer methods. With these servo amplifiers, a positioning system is configured without a Positioning module (command pulse). Positioning command is executed by CC-Link IE Field network, input/output signals, or RS-422/RS-485 communication (up to 32 axes). MR Configurator2 allows easy setting of the positioning data.

\* The program-based method is supported only by MR-J4-A-RJ.

### Point table method\*

### GF GF-RI A-RI Point table exa

Set position data (target position), servo motor speed, and acceleration/deceleration time constants in point table. Up to 255 points can be set in the point table, and setting the data is as easy as setting parameters. Perform positioning operation with a start signal after selecting the point table Nos.

\* For MR-J4-A-RJ, point table can be set with push buttons on the servo amplifier or with MR-PRU03 parameter unit.

| Point table No. | Position data |      | Acceleration<br>time constant | Deceleration<br>time constant | Dwell | Sub<br>function | M code |
|-----------------|---------------|------|-------------------------------|-------------------------------|-------|-----------------|--------|
| 1               | 1000          | 2000 | 200                           | 200                           | 0     | 1               | 1      |
| 2               | 2000          | 1600 | 100                           | 100                           | 0     | 0               | 2      |
| :               | :             |      | :                             | 1                             |       | 1               |        |
| 255             | 3000          | 3000 | 100                           | 100                           | 0     | 2               | 99     |



### Program method\*

Create positioning programs with dedicated commands, and perform positioning operation with a start signal after selecting the program Nos. The program-based method enables more complex positioning operation than the point table method. Maximum of 256 programs are settable. (The total number of steps of all programs: 640) \* MR Configurator2 is required to create programs.

Program example

A-RI



# Indexer method\*

GF GF-RJ A-RJ



Rotation direction specifying indexer or shortest rotating indexer can be set.

\* Fully closed loop control mode and linear servo motor control mode are not supported by the indexer method.



# Harmony with Man

The leading edge in safety and convenience, designed to harmonize with the way you work.

# Functions Compliant with IEC/EN 61800-5-2

STO (Safe torque off) and SS1<sup>'1</sup> (Safe stop 1) are integrated as standard, enabling the safety system to be configured easily in a machine.
By using STO, it is not necessary to turn off

- the control power of the servo amplifier, resulting in a shorter restart time and eliminating the necessity of home position return.
- •A magnetic contactor for preventing unexpected motor start is not needed."2
- •The safety level of STO is increased to SIL 3 from SIL 2.  $^{\rm '3}$



| IEC/EN 61800-5-2:2007 function | Safety level              |
|--------------------------------|---------------------------|
| STO (Safe torque off)          | Category 3 PL e, SIL 3 *3 |
| SS1 (Safe stop 1) <sup>1</sup> | Calegory 3 PL e, SIL 3    |

- \*1. Safety equipment (MR-J3-D05, safety programmable controller MELSEC QS/WS series, etc.) is required.
- \*2. For MR-J4 series servo amplifier, magnetic contactors are not required to meet the STO requirements. However, this illustration has a magnetic contactor installed to prevent servo alarms and electric shock.
- \*3. For Category 3 PL e, SIL 3, use compatible safety equipment and set the parameters. When MR-J3-D05 is used, safety level is Category 3 PL d, SIL 2.

# Category 4 PL e, SIL 3 with functional safety unit

Safety level is Category 4 PL e, SIL 3 when the safety signals are inputted directly to MR-D30 functional safety unit or through safety communication to the servo amplifier. The safety observation function is operated on the MR-D30, and therefore expansion of the safety observation function is possible independent of controllers.

Servo motors with functional safety are now available. (HG-KR\_W0C/HG-SR\_W0C/HG-JR\_W0C)



By CC-Link IE Field Network safety communiation



| IEC/EN 61800-5-2:2007 function                 | Safety level           |
|--|------------------------|
| STO (Safe torque off)                          |                        |
| SS1 (Safe stop 1)                              |                        |
| SS2 (Safe stop 2) 1                            |                        |
| SOS (Safe operating stop) <sup>1</sup>         | Category 4 PL e, SIL 3 |
| SLS (Safely-limited speed) <sup>*2</sup>       |                        |
| SBC (Safe brake control)                       |                        |
| SSM (Safe speed monitor) *2                    |                        |
| *1 Bequires the use of a servo motor with func | tional safety.         |

\*2. Safety level is Category 3 PL d, SIL 2 when the servo motor with functional safety is not used.

# **Tough Drive Function**

### Instantaneous power failure tough drive

When an instantaneous power failure is detected, this function allows the servo amplifier to use the electric energy charged in the main circuit capacitor in the servo amplifier to avoid an alarm occurrence, increasing the machine availability even with an unstable power supply.

### Vibration tough drive

Machine resonance suppression filter is automatically readjusted when a change in machine resonance frequency is detected by the servo amplifier, reducing unplanned machine downtime caused by age-related degradation.

# Large Capacity Drive Recorder

Servo data such as motor current and position command before and after the alarm occurrence are stored in non-volatile memory of the servo amplifier. Reading the servo data on MR Configurator2 helps you analyze the cause of the alarm.



Undervoltage

Operation continues even with

instantaneous power failure.

Servo motor speed

Vibration

detected

Motor current

Tough drive enabled

Tough drive disabled

Suppresses vibration by readjusting the machine resonance suppression filter.

# **Machine Diagnosis Function**

This function detects changes in mechanical parts (ball screw, guide, bearing, belt, etc.) by analyzing changes in machine friction, load moment of inertia, unbalanced torque, and vibration components from the data inside a servo amplifier, supporting timely maintenance of these parts. The following failure prediction functions are available with MR-J4-GF and notify the maintenance timing.

- Friction failure prediction function
- Vibration failure prediction function
- Total distance failure prediction function

### [Machine diagnosis function window on MR Configurator2]



# Harmony with the Environment

An evolution in eco-friendly design, and that's winning acclaim worldwide.

# 2-axis/3-axis Types for Energy-Saving, Miniaturized, and Low-Cost Machine

2-axis and 3-axis servo amplifiers are available for operating two and three servo motors, respectively. These servo amplifiers enable energy-saving, compact machine at lower cost. Different types of servo motors including rotary servo motors, linear servo motors, and direct drive motors are freely combined as long as the servo motors are compatible with the servo amplifier.



# Space-Saving with Industry's Smallest\* 3-axis Type

2-axis servo amplifier MR-J4W2-B requires 26% less installation space than two units of MR-J4-B. 3-axis servo amplifier MR-J4W3-B requires 30% less installation space than three units of MR-J4-B.

[Example of installation space for two units of each 100 W, 200 W, 400 W, and 750 W]



\* Based on Mitsubishi Electric research as of August 2018

# Reduced Wiring by Approx. 50% with 3-axis Type

The three axes of 3-axis servo amplifier MR-J4W3-B use the same connections for main and control circuit power, peripheral equipment, control signal wire, etc. Thus, the number of wirings and devices is greatly reduced.



[Comparison of the number of wirings]

# **Energy-Conservation with Common DC Bus Connection**

When multiple servo amplifiers and drive units Driving section Converter section Regenerative energy A-axis motor speed are connected to the MR-CV power \* ₭ regeneration converter unit by a common DC A-axis motor Deceleration bus connection, the regenerative energy of Driving energy Time one axis is used for driving other axes, К B-axis motor speed B-axis motor contributing to energy-conservation. Driving energy The multi-axis servo amplifier has the same Acceleration Time effect. C-axis motor C-axis motor speed Regenerative energy of A-axis motor is used for B and C-axis motors. Acceleration Time

# Further Energy-Conservation with Power Regeneration System



Continuous driving axis -MR-J4-DU\_B

# Heritage

A heritage of trust and continuity - the hallmark of every MELSERVO product.

# **Easy Replacement of MR-J3 Series**

MR-J4-B/MR-J4-A has the same mounting dimensions<sup>\*1</sup> with MR-J3-B/MR-J3-A. HG rotary servo motor series has the same mounting dimensions"2 and uses the same option cables for the power, the encoder\*3, and the electromagnetic brake as HF series or HC-RP/HC-UP series.



\*1. Mounting dimensions are smaller for servo amplifiers rated 200 V 5 kW, 400 V 3.5 kW, 200 V/400 V 11 kW, and 200 V/400 V 15 kW.
\*2. For replacing HA-LP series with HG-JR series, contact your local sales office for more detail.

\*3. HG-JR series of 11 kW to 55 kW uses a different encoder cable from HF-JP series.

# Supporting Replacement of MR-J2-Super Series

MELSERVO-J4 series product lines include general-purpose interface, positioning function, and SSCNET III/H interface. MELSERVO-J4 series is compatible with a wide variety of command interface and also replaceable from MELSERVO-J2S series.



We provide support for the renewal with the following materials from the catalog of renewal introduction, the handbook with detailed information to the instruction manual for the renewal tool to use the existing wiring



Transition from MELSERVO-J3/J3W Series to J4 Series Handbook L(NA)03127 This handbook explains how to replace your

MR-J3/J3W with MR-J4 series.



Transition from MELSERVO-J2-Super/J2M Series to J4 Series Handbook L(NA)03093

This handbook explains how to replace your MR-J2S/J2M with MR-J4 series.



MR-J2S Renewal Tool Catalog X901307-312

This guide introduces a renewal tool for replacing MR-J2S with MR-J4. The renewal tool allows to use the existing wiring and mounting holes, making the replacement simple and fast.

Mitsubishi Electric System & Service Co., Ltd.

# ~Reliable Basic Performance and Advanced Ease-of-Use~

# **MELSERVO-JE** series

# [Easy To Use]

- One-touch tuning adjusts servo gains with one-touch ease.
- Instantaneous power failure tough drive function and a large capacity capacitor reduce machine downtime.
- MR-JE-C and MR-JE-B support absolute position detection system.
- MR-JE-C and MR-JE-A have a built-in positioning function. MR-JE-A is equipped with advanced functions such as simple cam and position compensation.

# [High Performance]

- MR-JE series is compatible with various networks including CC-Link IE Field Network Basic, SSCNET III/H, and MODBUS®.
- The dedicated engine enables speed frequency response of 2.0 kHz, shortening the cycle time.
- The large capacity main circuit capacitor allows the regenerative energy to be used effectively.

# [Global Standard]

- Global servo, MR-JE series, complies with global standards as standard.
- Command pulse input and digital input/output are compatible with both sink and source type connections.

# MR-JE-C

Ethernet compatible servo amplifier

# CC-Línk 📙 🖬 ield Basic



MR-JE-B SSCNET III/H compatible servo amplifier





MR-JE-A General-purpose interface compatible servo amplifier



MR-JE-C supports Ethernet communication (CC-Link IE Field Network Basic, SLMP, and MODBUS®/TCP) and RS-485 communication (MODBUS® RTU), and enables a flexible system configuration. In addition, the MR-JE-C has a built-in positioning function (point table method and indexer method), making positioning operation easy without a Positioning module.

| Command interface      | CC-Link IE Field Network Basic, SLMP, and MODBUS <sup>®</sup> /TCP,<br>MODBUS <sup>®</sup> RTU |
|------------------------|--|
| Control mode           | Position/Speed/Torque  |
| Power supply           | 200 V AC   |
| Capacity range         | 0.1 kW to 3 kW   |
| Compatible servo motor | Rotary servo motor   |

MR-JE-B is compatible with SSCNET III/H, optical servo system controller network that enables a high-response and multi-axis system with high synchronous performance and less wiring. In addition, absolute position detection system can be configured easily with the MR-JE-B servo amplifiers.

| Command interface      | SSCNET III/H          |
|------------------------|-----------------------|
| Control mode           | Position/Speed/Torque |
| Power supply           | 200 V AC              |
| Capacity range         | 0.1 kW to 3 kW        |
| Compatible servo motor | Rotary servo motor    |

Pulse train and analog input, etc., are provided as a standard for the command interface. Position, speed, and torque control modes are available, and the modes can be switched with an input device. The MR-JE-A has a built-in positioning function, being compatible with MODBUS<sup>®</sup>, simple cam, and mark sensor input compensation.

| Command interface      | Pulse train/Analog/RS-422/MODBUS® RTU |
|------------------------|---------------------------------------|
| Control mode           | Position/Speed/Torque                 |
| Power supply           | 200 V AC                              |
| Capacity range         | 0.1 kW to 3 kW                        |
| Compatible servo motor | Rotary servo motor                    |

# Servo Motors

# From rotary to linear and direct drive motors

Rotary servo motors are available in capacities from 10 W to 220 kW. Linear servo motors and direct drive motors satisfy new needs in driving control by providing high rigidity, performance and flexibility in system configurations unique to a direct drive.

Rotary servo motor: A wide range of capacities and series for various system applications

# HG series for MELSERVO-J4 series

### HG-KR/HG-MR



HG-JR

HG-SR

### **HG-AK**

HG-RR

HG-UR



# Equipped with High-Resolution Absolute Position Encoder

Servo motors are equipped with a high-resolution absolute position encoder of 4,194,304 pulses/rev (22-bit) as standard. Positioning accuracy is increased.

\* 262,144 pulses/rev (18-bit) for HG-AK series.

# Improved Environmental Resistance

Ingress protection<sup>2</sup> of servo motors: HG-KR/HG-MR/HG-RR/HG-UR: IP65

HG-SR/HG-JR: IP67<sup>\*1</sup>

HG-AK: IP55

- \*1. HG-JR1000 r/min series 15 kW or larger, HG-JR1500 r/min series 22 kW or larger,
- and HG-JR 2000 r/min series are rated IP44.
- \*2. The shaft-through portion is excluded.

# **Cable Leading Direction**

Cables for power, encoder, and electromagnetic brake are capable of connecting either in direction or in opposite direction of the load side, depending on the cable selection. (HG-KR and HG-MR series)





# **Reduced Torque Ripple during Conduction**

The torque ripple is reduced owing to the optimized combination of the numbers of the motor poles and the slots. Thereby, smooth rotation is achieved even during a low-speed operation which is more likely affected by the torque ripple, improving the operation stability.



# HG series for MELSERVO-JE series

# HG-KN



Capacity: 0.1 kW to 0.75 kW Rated speed: 3000 r/min

- [Application example]
- ●Inserters, mounters and bonders ●PCB drilling machines
- ●In-circuit testers and label printers ●Knitting and embroidery machines

Small capacity, low inertia. Perfect for general-purpose industrial machines.

Compact robots and robot hand sections

Medium capacity, medium inertia. Suitable for machines having large load inertia. Capacity: 0.5 kW to 3 kW Rated speed: 2000 r/min [Application example] •Material handling systems •Dedicated machines •Robots •Loaders and unloaders •Winders, tension units •Turrets •X-Y tables





Linear servo motor: Suitable for linear motion systems requiring high speed and accuracy

# LM series for MELSERVO-J4 series

| LM-H3 |             | Maximum speed: 3 m/s<br>Rated thrust: 70 N to 960 N<br>Core type suitable for space-saving.<br>The magnetic attraction force contributes to high rigidity.   |
|-------|-------------|--|
| LM-F  |             | Maximum speed: 2 m/s<br>Rated thrust: 300 N to 3000 N (natural cooling), 600 N to 6000 N (liquid cooling)<br>Core type compact linear servo motor.<br>The integrated liquid-cooling system doubles the continuous thrust.<br>The magnetic attraction force contributes to high rigidity. |
| LM-K2 | 3-3-3-2-3-2 | Maximum speed: 2 m/s<br>Rated thrust: 120 N to 2400 N<br>Core type with magnetic attraction counter-force.<br>The magnetic attraction counter-force structure extends life of the linear guides and<br>contributes to lowering audible noise.  |
| LM-U2 | the survey  | Maximum speed: 2 m/s<br>Rated thrust: 50 N to 800 N<br>Coreless type without cogging resulting in small speed fluctuation.<br>The structure with no magnetic attraction force extends life of the linear guides.   |

# **Sophisticated Performance**

Supporting maximum speed of 3 m/s (LM-H3 series) and maximum thrust of 150 N to 18000 N.

Small size and high thrust are achieved by the increased winding density and the optimized core and magnet geometries as a result of electromagnetic field analysis.

Diverse product lines include core, liquid-cooling core, magnetic attraction counter-force core, and coreless types.

A/B/Z-phase differential output type linear encoders are also supported by MR-J4-GF-RJ/MR-J4-B-RJ/MR-J4-A-RJ servo amplifiers.

An advanced system including high-accuracy tandem synchronous control can be configured with CC-Link IE Field Network or SSCNET III/H compatible controller.

### [Application example]



Multi-head configuration



# **Application Example**

[Machine tools XYZ stage]



[Semiconductor/FPD manufacturing systems]



[Screen printing systems]



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Direct drive motor: For compact and simplified machine driving part with high-accuracy control

# TM series for MELSERVO-J4 series

# TM-RG2M





Motor outer diameter: \$\phi130 mm, \$\phi180 mm, and \$\phi230 mm Rated torque: 2.2 N·m to 9 N·m Low-profile direct drive motor available in two types: flange type (with pilot) and table type (with positioning pin holes)

TM-RFM



Motor outer diameter:  $\phi$ 130 mm,  $\phi$ 180 mm,  $\phi$ 230 mm,  $\phi$ 330 mm Rated torque: 2 N·m to 240 N·m High-rigidity direct drive motor for high-torque

# **Sophisticated Performance**

[High performance with the latest technologies]

Our latest magnetic design and winding technologies enable high torque density. In addition, extremely smooth rotation is achieved by the minimized torque ripple.

[Compact and low-profile design]

Due to high level of structural design technology, compact and low-profile design is achieved. This design enables a small mounting space and a low center of gravity.

[High-resolution absolute position encoder]

The direct drive motor is equipped with a high-resolution absolute position encoder (1,048,576 to 4,194,304 pulses/rev) as standard. High-accuracy machine is achieved.

[Hollow shaft diameter range: ø20 mm to 104 mm]

The motor is equipped with a large hollow shaft resulting from using bearing and encoder with large diameter. It allows cables and air tubing to pass through.

# **Application Example**

Suitable for low speed and high torque applications.

[Coating and vapor deposition systems]

[Index table for machine tools]





[Rotary axis for polishing systems]





[Spin-type cleaning systems for FPD/semiconductor] [FPD/semiconductor testing systems (XY0 tables)]

[Rotary axis for material handling robots]



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# **Engineering Software**



# FA Integrated Engineering Software **MELSOFT iQ Works**

MELSOFT iQ Works is an integrated software suite consisting of GX Works3, MT Works2, GT Works3, RT ToolBox3, FR Configurator2, MR Configurator2 and CW Configurator, which are programming software for each respective product. Integration is further enhanced with MELSOFT Navigator as the central system configuration incorporating an easy-to-use, graphical user interface with additional project-sharing features such as system labels and parameters. The advantages of this powerful integrated software suite are that system design is made much easier with a substantial reduction in repetitious tasks, cutting down on errors while helping to reduce the overall TCO.



# System management software MELSOFT Navigator

System level graphic-based configuration tool that simplifies the system design by providing a visual representation of the system. System management features such as system-wide parameterization, labels and block reading of project data are also included.

# Programmable controller engineering software MELSOFT GX Works3

GX Works3 is the latest generation of programming and maintenance software offered by Mitsubishi Electric specifically designed for the MELSEC iQ-R series control system. It includes many new features such as graphic-based system configuration, integrated motion control setup, multiple language support, providing an intuitive engineering environment solution.

### HMI/GOT screen design software MELSOFT GT Works3

This graphic operation terminal (GOT) screen creation software is designed with three main features—simplicity, graphics design and operation ease—that help to create graphic screens in fewer steps.

# Motion controller engineering software MELSOFT MT Works2

This motion control design and maintenance software includes intuitive graphic-based programming together with a digital oscilloscope simulator.

# Servo setup software MELSOFT MR Configurator2

Tuning, monitor display, diagnosis, reading/writing parameters, and test operations are easily performed on a personal computer. This powerful software tool supports a stable machine system and optimum control, and moreover, shortens setup time.

- Robot engineering software MELSOFT RT ToolBox3
- Inverter setup software MELSOFT FR Configurator2
- C Controller setting and monitoring tool MELSOFT CW Configurator

# Fully supporting all your needs from model selection, system design, startup to maintenance with diverse software

MELSOFT is the FA integrated engineering software that demonstrates their abilities in various FA scenes including designing, debugging and startup, and operation and maintenance to facilitate all aspects from specification review to daily data collection.

| Programmable Controller Engineering Software  | Motion Controller Engineering Software  | Servo Setup Software   |
|---|---|--|
| MELSOFT <b>GX Works3</b>  | MELSOFT MT Works2   | MELSOFT MR Configurator2   |
| All-in-one tool<br>for quick and easy startup<br>This software supports the engineering process<br>- from creation of a sequence program, parameter<br>settings of the Simple Motion module, and creation<br>of a positioning data table and cam data through<br>startup, debugging, and maintenance. | <b>Comprehensibly supporting Motion</b><br><b>controller design and maintenance</b><br>With features including Motion SFC programming,<br>parameter settings, and the digital oscilloscope function,<br>this software supports the engineering process -from<br>system configuration and programming through<br>debugging and maintenance of the Motion controller. | User-friendly software for easy<br>setup, tuning, and operation<br>Tuning, monitoring, diagnosis, reading/<br>writing parameters, and test operations are<br>easily performed. |

# System Design

# System configuration



-

GX MT Works3 Works2

Amplifier setting

Servo amplifiers and modules are set easily with the graphical system setting screen.



# Servo data setting

One-point help allows you to set parameters without manuals.

Entering just the machine specifications (reduction ratio, ball screw pitch, etc.) sets the electric gear.





Electronic gear setting



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# **Module configuration**

Each parameter is set from the module configuration screen.



# Copying servo data

All had



GX Works3

Copy & paste of the data between axes is easy.

# Programming

# Positioning data setting



Functions, such as Data setting assistant and Automatic calculation of auxiliary arc, simplify the setting input process of positioning data.



# Synchronous control parameter



The synchronous control parameter is easily set using software instead of controlling mechanically with physical gears, shafts, speed change gears or cams.





Simulation can be executed without an actual

machine during the debugging process.

# Cam data creation

Simulation



Various cam patterns are created more freely and flexibly.



Programming



User-friendly functions make Motion controller program development easier.



# Cam data list



The created cam data are easily viewed as thumbnails.

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# **Startup and Adjustment**

# **Monitor**



The required items and axes are selected from various monitoring information.

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# **Digital oscilloscope**



Data collection and waveform display which are synchronized with the Motion operation cycle greatly help you check operation and perform troubleshooting.



# Multi-axis adjustment



The multi-axis adjustment function enables easy servo adjustment and quick startup for machines executing multi-axis simultaneous operation, such as a tandem configuration.





# Servo assistant function

Complete setting up the servo amplifier just by following guidance displays.



# **One-touch tuning function**

With the ease of clicking the start button, adjustments including estimating load to motor inertia ratio, adjusting gain, and suppressing machine resonance are automatically performed for the maximum servo performance.

Display adjustment results.

# Parameter setting function

Display parameter setting in list or visual formats, and set parameters by selecting from the drop down list.



Display details of relevant parameters in a docking window.

# **Tuning function**

Adjust control gain finely on the [Tuning] window manually for further performance after the one-touch tuning.



# **Monitor function**

Monitor the operation information on the [Display all] window. The power consumption can also be monitored without additional measurement equipment.

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# **Alarm display**

MR-J4 series displays the alarm No. in three digits to show the servo alarm in more details, making troubleshooting easy.



# Select the most suitable motor for your machine Capacity selection software **MRZJW3-MOTSZ111E**

Select the most suitable servo motor, servo amplifier, and regenerative option for your machine just by setting machine specifications and operation pattern.

Select the operation pattern from either position control mode or speed control mode. The capacity selection software is available for free download. Contact your local sales office for more details.



# **CC-Link IE Field Network**

# Ethernet-based open network, CC-Link IE Field Network -

## All-rounder network opens up new areas of control

This Ethernet-based open network is designed to simultaneously handle distributed control, I/O control, safety control, and Motion control.

# **Two Times Faster Operation Cycle**



The operation cycle of 0.5 ms, two times faster than the previous model, enables smoother machine control.

Smooth control of synchronization, cam control, and S-curve acceleration/deceleration improves the product quality with a shorter cycle time.

# **Motion Control Achieved**



The CC-Link IE Field Network is equipped with Motion function in the cyclic communication bandwidth. Synchronous communication with the servo amplifiers becomes possible, offering high-speed and high-accuracy positioning, synchronous control, and cam control.

# Easy Startup



Selecting each field device on the screen of CC-Link IE Field configuration via drag & drop enables easy parameter settings. An addition or a change of field devices are also easily made by modifying the parameters.

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# **All-Rounder Network**



# **Flexible Network Topology**



CC-Link IE Field Network is an Ethernet-based open network. The highly flexible wiring of CC-Link IE Field enables versatile control from I/O control to Motion control over the single network. Cables and connectors are highly available in the world as CC-Link IE Field Network is based on the Ethernet.

\* Up to 32 servo amplifiers (motion mode) are connectable.

Slave stations:

RD77GF: 120 stations

(including the number of servo amplifiers in motion mode) QD77GF: 120 stations

(16 servo amplifiers in motion mode + 104 I/O devices)

Star, line, and star/line mixed topologies are available for a network configuration by using a switching hub.

When using star topology, be sure to use the following switching hubs: Intelligent hub: NZ2MHG-T8F2

Industrial switching hub: DT135TX (manufactured by Mitsubishi Electric System & Service Co., Ltd.)

# **Synchronous Communication Function**



The operation timings of multiple slave units match since the synchronous communication compatible slave devices operate at the operation cycle of the Simple Motion module.



(1) Interrupts (2) Operation processing (3) Setting of command value

# **CC-Link IE Field Network Basic**

With recent trends of IoT<sup>-1</sup>, network connection of devices and equipment for small-scale systems are becoming more mainstream. CC-Link IE Field Network Basic realizes easier network integration of Ethernet devices, as its cyclic communications stack is software-based, without requiring a dedicated ASIC helping to reduce implementation costs for device partners. Transparent communications are achieved by utilizing SLMP<sup>-2</sup> that enables seamless connectivity within all levels of manufacturing.

CC-Link IE Field Network Basic is supported by MR-J4-GF and MR-JE-C.



# **SSCNET III/H**

# The blazingly fast speed and response of 150 Mbps full-duplex baud rate SSCNET III/H optical networking

SSCNET III/H is a high-speed servo system controller network employing fiber optic cables, enabling high precision synchronization. The communication cycle as fast as 0.222 ms increases responsivity and reduces cycle time of machine. The dedicated fiber optic cable reduces the wiring and makes the setting up so simple.



# Synchronous communication



Synchronous communication is achieved with SSCNET III/H, offering technical advantages for machines in printing and food processing industry that require deterministic control.

# Improved Noise Tolerance by Optical Communication



The fiber-optic cables thoroughly shut out noise that enters from the power cable or external devices. Noise tolerance is dramatically improved as compared to metal cables.

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# Long Distance Wiring up to 3200 m



Long distance wiring is possible up to 3200 m per system (maximum of 100 m between stations  $\times$  32 axes), suitable for large-scale systems.

Maximum overall distance per systemStandard code/standard cable: 640 m (20 m × 32 axes)Long distance cable:3200 m (100 m × 32 axes)

# **Central Control with Network**



Large amounts of servo data are exchanged in real-time between the controller and the servo amplifier. Using MR Configurator2 on a personal computer that is connected to the Motion controller or the Simple Motion module helps consolidate information, such as parameter settings and monitoring for the multiple servo amplifiers.

# **Network Topology**



Star and line topologies are available with MR-MV200 optical hub unit through SSCNET III/H for a network configuration. Maintenance can be executed without stopping the whole system, and thus the machine availability will be increased.

# I/O Signals Synchronized with Motion Control



MR-MT2000 series sensing modules including the I/O module, analog I/O module, pulse I/O module, and encoder I/F module are connected to SSCNET III/H.

These various modules enable a faster, more accurate machine operation by synchronizing the I/Os of a general-purpose pulse train driver, sensor, and SSI encoder with the motion control.

# **Selection of Servo System Controller**

Select the type of servo system controller roughly on the basis of control method after selecting a PLC CPU. Next, select the optimal servo system controller that suits your application on the basis of connecting devices, performance/program types, and functions.



# **Model Selection of PLC CPU and Controller**

# Medium- to large-scale control

# MELSEC iQ R



MELSEG Q<sub>series</sub>



A next-generation programmable automation controller (PAC), the MELSEC iQ-R series resolves your tasks as the core of the automation system by integrating high-performance capabilities based on the high-end iQ-R system bus, inter-module synchronization, and high precision processing achieved by synchronization between high-speed networks.

The first to incorporate the multiple CPU architecture, the MELSEC-Q series wide-range of CPUs enables control of multiple operations, improving the performance and scalability of the overall production system.

# Small- to medium-scale control



The MELSEC-L series is a baseless highly scalable controller ideal for applications having limited space. With various I/O functionality embedded into the CPU module, high performance is achieved in a compact body.

# Small-scale and stand-alone









Designed to provide outstanding performance and superior drive control, the MELSEC iQ-F series is a high-performance compact-class controller with a rich assortment of integrated functions.

Incorporating abundant features with a flexible system configuration, the MELSEC-F series has a power supply, CPU, and I/Os into a single compact body.

# Motion control by C Language based programming



High-response servo control can be performed with a combination of the Position Board and a personal computer, or the C Controller Interface Module and the C Controller.

# **Model Selection by Control Method**

Select the controller on the basis of control method, program, and command interface.



\* For RnMTCPU, add-on libraries can be additionally installed. With "G-code control add-on library" (not free of charge), the controller can control a processing machine using general-purpose AC servo system. With an add-on library "machine library" (free of charge), the controller can control a simplified robot (link configuration).


## Model Selection of PLC CPU

Select the PLC CPU in consideration of the size and expandability of the equipment.



## **Product Lines**

| Programmable              | Model                              |                                  | Engineering                          | Command   |                    | Melseri/o-J4   | MELSER             | melseri⁄o-JE   |  |  |
|---------------------------|------------------------------------|----------------------------------|--------------------------------------|---|--------------------|----------------|--------------------|----------------|--|--|
| controller                |                                    |                                  | software                             | interface                                       | Servo<br>amplifier | Servo<br>motor | Servo<br>amplifier | Servo<br>motor |  |  |
| MELSEC<br>iQ-R<br>series  | CPU module                         | RnCPU<br>RnENCPU                 | GX Works3                            | CC-Línk <mark>IE</mark> 🖬 ield Basic            |                    | <b>*</b>       | MR-JE-C            | -10            |  |  |
|                           | Simple<br>Motion<br>module         | RD77GF                           | GX Works3                            | CC-Línk <mark>IE B</mark> ield                  | MR-J4-GF           |                | -                  | _              |  |  |
|                           |                                    | RD77MS                           | GX Works3                            |   |                    | <b>*</b>       | MR-JE-B            | 10             |  |  |
|                           | Motion<br>controller               | RnMTCPU                          | GX Works3<br>MT Works2               |   | MR-J4(W)-B         |                | -                  | _              |  |  |
|                           | Positioning<br>module              | RD75P<br>RD75D                   | GX Works3                            | Transistor output<br>Differential driver output | MR-J4-A            |                | MR-JE-C<br>MR-JE-A | -10            |  |  |
|                           | Simple                             | QD77GF                           | GX Works2                            | CC-Línk IE <b>B</b> iold                        | MR-J4-GF           |                | -                  | _              |  |  |
|                           | Motion<br>module                   | QD77MS                           | GX Works2                            |   |                    | <b>*</b>       | MR-JE-B            | -              |  |  |
| MELSEC-<br>Q series<br>*3 | Motion<br>controller               | Q17nDSCPU<br>Q170MSCPU           | GX Works2<br>MT Works2               |   | MR-J4(W)-B         |                | -                  | _              |  |  |
|                           | Positioning<br>module              | QD75PN<br>QD75DN                 | GX Works2                            | Transistor output<br>Differential driver output | MR-J4-A            |                | MR-JE-C            | _              |  |  |
|                           |                                    | QD70P<br>QD70D                   | GX Works2                            | Transistor output<br>Differential driver output |                    | -100           | MR-JE-A            | -100           |  |  |
|                           | CPU module                         | LCPU                             | GX Works2                            | Transistor output                               | MR-J4-A            |                | MR-JE-C<br>MR-JE-A | -10            |  |  |
| MELSEC-<br>L series<br>*3 | Simple<br>Motion<br>module         | LD77MS                           | GX Works2                            |   | MR-J4(W)-B         |                | MR-JE-B            | -10            |  |  |
|                           | Positioning<br>module              | LD75P<br>LD75D                   | GX Works2                            | Transistor output<br>Differential driver output | MR-J4-A            |                | MR-JE-C<br>MR-JE-A | -10            |  |  |
|                           | CPU module                         | FX5U                             | GX Works3                            | CC-Línk IE 🖬 ield Basic                         | MR-J4-GF           |                | MR-JE-C            | -              |  |  |
| MELSEC<br>iQ-F<br>series  |                                    | FX5UC                            | GX Works3                            | Transistor output                               | MR-J4-A            |                | MR-JE-A<br>MR-JE-C | -10            |  |  |
|                           | Simple<br>Motion<br>module         | FX5-40SSC-S<br>FX5-80SSC-S       | GX Works3                            | <b>SSCNETIII/H</b>                              | MR-J4(W)-B         |                | MR-JE-B            | -100           |  |  |
| MELSEC-                   | CPU module                         | FX3U<br>FX3UC                    | GX Works2                            | Transistor output                               |                    | <b>*</b>       | MR-JE-C            | _              |  |  |
| F series                  | Positioning<br>module              | FX₃u-1PG                         | GX Works2                            | Transistor output                               | MR-J4-A            | -1990          | MR-JE-A            | -100           |  |  |
| Personal                  | Board type<br>controllers          | MR-EM340GF                       | EM Software<br>Development Kit<br>*1 | CC-Línk IE Bield                                | MR-J4-GF           |                | -                  | _              |  |  |
| computer                  |                                    | MR-MC2_0<br>MR-MC2_1<br>MR-MC341 | *1                                   |   | MR-J4(W)-B         |                | MR-JE-B            | -10            |  |  |
| /IELSEC-<br>Q series      | C Language<br>compatible<br>module | Q173SCCF                         | *2                                   | <b>SSCNETII/H</b>                               | MR-J4(W)-B         |                | MR-JE-B            | -17            |  |  |

\*1. Be sure to prepare the development environment in which Microsoft Visual Studio<sup>®</sup> can be used.
 \*2. CW Workbench/Wind River Workbench, and Setting/monitoring tool for the C Language Controllers
 \*3. MELSEC Q and MELSEC L series also support CC-Link IE Field Network Basic.

## **Performance/Program**

|                            |                                    |                                  | Maximum<br>number                |                               | Positioning program     |                                     |               |  |                     |            |                    |
|----------------------------|------------------------------------|----------------------------------|----------------------------------|-------------------------------|-------------------------|-------------------------------------|---------------|--|---------------------|------------|--------------------|
| Programmable<br>controller | Mc                                 | odel                             | of<br>control<br>axes            | Operation<br>cycle            | Motion<br>profile table | Synchronous<br>control<br>parameter | Motion<br>SFC | G-code <sup>*1</sup> ,<br>Machine<br>control | Sequence<br>program | C language | Electronic<br>gear |
|                            | CPU module                         | RnCPU<br>RnENCPU                 | Depends on the<br>master station | Depends on the master station | _                       | _                                   | -             | -  | •                   | _          | -                  |
|                            | Simple<br>Motion                   | RD77GF                           | 32                               | 0.5 ms or longer              | •                       | •                                   | _             | _  | •                   | _          | •                  |
| MELSEC<br>iQ-R<br>series   | module                             | RD77MS                           | 16                               | 0.444 ms or longer            | •                       | •                                   | _             | _  | ٠                   | _          | ٠                  |
|                            | Motion<br>controller               | RnMTCPU                          | 64                               | 0.222 ms or longer            | _                       | ٠                                   | ٠             | ٠  | ٠                   | _          | ٠                  |
|                            | Positioning<br>module              | RD75P<br>RD75D                   | 4                                | _                             | •                       | -                                   | _             | _  | •                   | _          | •                  |
|                            | Simple<br>Motion                   | QD77GF                           | 16                               | 1 ms or longer                | •                       | •                                   | _             | _  | •                   | _          | •                  |
|                            | module                             | QD77MS                           | 16                               | 0.888 ms or longer            | •                       | •                                   | _             | _  | •                   | _          | •                  |
| MELSEC-<br>Q series        | Motion<br>controller               | Q17nDSCPU<br>Q170MSCPU           | 32<br>16                         | 0.222 ms or longer            | -                       | •                                   | ٠             | -  | •                   | -          | ٠                  |
|                            | Positioning<br>module              | QD75PN<br>QD75DN                 | 4                                | -                             | •                       | _                                   | _             | _  | •                   | _          | •                  |
|                            |                                    | QD70P<br>QD70D                   | 8                                | _                             | •                       | -                                   | _             | _  | •                   | _          | -                  |
|                            | CPU module                         | LCPU                             | 2                                | -                             | •                       | _                                   | _             | -  | •                   | _          | -                  |
| MELSEC-<br>L series        | Simple<br>Motion<br>module         | LD77MS                           | 16                               | 0.888 ms or longer            | •                       | ٠                                   | _             | _  | •                   | _          | •                  |
|                            | Positioning<br>module              | LD75P<br>LD75D                   | 4                                | _                             | •                       | _                                   | _             | _  | •                   | _          | •                  |
|                            | CPU module                         | FX5U<br>FX5UC                    | Depends on the<br>master station | Depends on the master station | -                       | _                                   | -             | -  | •                   | _          | -                  |
| MELSEC<br>iQ-F<br>series   | CPU module                         | FX5U<br>FX5UC                    | 4                                | _                             | _                       | _                                   | _             | _  | •                   | _          | -                  |
|                            | Simple<br>Motion<br>module         | FX5-40SSC-S<br>FX5-80SSC-S       | 4<br>8                           | 0.888 ms or longer            | •                       | •                                   | _             | _  | •                   | _          | ٠                  |
| MELSEC-                    | CPU module                         | FХзи<br>FХзис                    | 3                                | _                             | _                       | -                                   | _             | _  | •                   | _          | -                  |
| F series                   | Positioning<br>module              | FX3U-1PG                         | 1                                | _                             | _                       | -                                   | _             | -  | •                   | _          | -                  |
| Personal                   | Board type                         | MR-EM340GF                       | 16                               | 0.5 ms or longer              | •                       | •                                   | _             | -  | -                   | •          | •                  |
| computer                   | controllers                        | MR-MC2_0<br>MR-MC2_1<br>MR-MC341 | 20<br>32<br>64                   | 0.222 ms or longer            | •                       | -                                   | -             | -  | -                   | •          | •                  |
| MELSEC-<br>Q series        | C Language<br>compatible<br>module | Q173SCCF                         | 20                               | 0.222 ms or longer            | •                       | _                                   | _             | _  | _                   | •          | •                  |

\*1. "G-code control add-on library" (provided for a fee) is additionally required. With the library, control of a processing machine using AC servo is possible.

# **Function comparison**

|  | MELSEC iQ-R                                |   |                                  |                                      | MEI SEC O                      |                                |   |  |  |
|--|--|---|----------------------------------|--------------------------------------|--------------------------------|--------------------------------|---|--|--|
|  |  |   |                                  | MELSEC-Q                             |                                |                                |   |  |  |
|  | RD77GF4<br>RD77GF8<br>RD77GF16<br>RD77GF32 | RD77MS2<br>RD77MS4<br>RD77MS8<br>RD77MS16 | R16MTCPU<br>R32MTCPU<br>R64MTCPU | RD75P2<br>RD75D2<br>RD75P4<br>RD75D4 | QD77GF4<br>QD77GF8<br>QD77GF16 | QD77MS2<br>QD77MS4<br>QD77MS16 | Q172DSCPU<br>Q173DSCPU<br>Q170MSCPU<br>Q170MSCPU-S1 | QD75P1N<br>QD75D1N<br>QD75P2N<br>QD75D2N<br>QD75P4N<br>QD75D4N |  |
| Position control                           | •  | •   | •                                | •                                    | •                              | •                              | •   | ٠  |  |
| Speed control                              | •  | •   | •                                | •                                    | •                              | •                              | •   | ٠  |  |
| Torque control                             | •  | •   | •                                | -                                    | •                              | •                              | ٠   | -  |  |
| Tightening & press-fit control             | _  | •   | •                                | -                                    | —                              | •                              | •   | -  |  |
| Advanced synchronous control               | •  | •   | •                                | -                                    | •                              | •                              | •   | -  |  |
| Cam control                                | •  | •   | •                                | _                                    | •                              | •                              | •   | -  |  |
| Linear interpolation                       | •  | •   | •                                | •                                    | •                              | •                              | •   | ٠  |  |
| Circular interpolation                     | •  | •   | •                                | •                                    | •                              | •                              | •   | •  |  |
| Continuous trajectory control              | •  | •   | •                                | •                                    | •                              | •                              | •   | •  |  |
| Speed/position switching control           | •  | •   | •                                | •                                    | •                              | •                              | •   | •  |  |
| Position follow-up control                 | -  | -   | •                                | -                                    | -                              | -                              | •   | -  |  |
| Helical interpolation                      | •  | •   | •                                | •                                    | -                              | -                              | •   | •  |  |
| Trapezoidal acceleration/deceleration      | •  | •   | •                                | •                                    | •                              | •                              | •   | ٠  |  |
| S-curve acceleration/deceleration          | •  | •   | •                                | •                                    | •                              | •                              | •   | ٠  |  |
| Advanced S-curve acceleration/deceleration | _  | _   | •                                | _                                    | _                              | _                              | •   | _  |  |
| JOG operation                              | •  | •   | •                                | •                                    | ٠                              | ٠                              | •   | ٠  |  |
| Manual pulse generator operation           | •  | •   | •                                | •                                    | •                              | •                              | •   | ٠  |  |
| Current value change                       | •  | •   | •                                | •                                    | ٠                              | ٠                              | •   | ٠  |  |
| Target position change                     | •  | •   | •                                | •                                    | •                              | ٠                              | ٠   | ٠  |  |
| Speed change                               | •  | •   | •                                | •                                    | ٠                              | ٠                              | •   | ٠  |  |
| Override                                   | •  | •   | •                                | •                                    | •                              | •                              | -   | ٠  |  |
| Acceleration/deceleration time change      | •  | •   | •                                | •                                    | ٠                              | •                              | •   | ٠  |  |
| Home position return                       | •  | •   | •                                | •                                    | •                              | •                              | •   | •  |  |
| Absolute position system                   | •  | •   | •                                | Simple ver.                          | •                              | •                              | •   | Simple ver.  |  |
| Unlimited length feed                      | •  | •   | •                                | •                                    | •                              | •                              | •   | ٠  |  |
| Optional data monitor                      | •  | •   | •                                | -                                    | •                              | •                              | •   | -  |  |
| Mark detection                             | •  | •   | •                                | -                                    | •                              | •                              | •   | -  |  |
| Event history                              | •  | •   | •                                | •                                    | -                              | -                              | -   | -  |  |
| Cam auto-generation                        | •  | •   | •                                | -                                    | •                              | ٠                              | •   | -  |  |
| Driver communication                       | -  | •   | •                                | -                                    | -                              | •                              | •   | -  |  |
| Digital oscilloscope                       | •  | •   | •                                | -                                    | •                              | •                              | •   | -  |  |
| Vision system                              | -  | -   | •                                | -                                    | -                              | -                              | •   | -  |  |
| Security key                               | -  | -   | •                                | -                                    | —                              | _                              | •   | —  |  |

| MELSEC-Q                             | MELS                           | SEC-L  | MELSE                      | C iQ-F        | MELS          | SEC-F       | MELSEC-Q | Personal   | computer   |
|--------------------------------------|--------------------------------|--|----------------------------|---------------|---------------|-------------|----------|------------|--|
| QD70P4<br>QD70D4<br>QD70P8<br>QD70D8 | LD77MS2<br>LD77MS4<br>LD77MS16 | LD75P1<br>LD75D1<br>LD75P2<br>LD75D2<br>LD75P4<br>LD75D4 | FX5-40SSC-S<br>FX5-80SSC-S | FX5U<br>FX5UC | FX3U<br>FX3uc | FX₃∪-1PG    | Q173SCCF | MR-EM340GF | MR-MC240<br>MR-MC241<br>MR-MC241<br>MR-MC220U3<br>MR-MC220U6<br>MR-MC210<br>MR-MC211 |
| •                                    | •                              | •  | •                          | •             | •             | •           | •        | •          | •  |
| -                                    | ٠                              | •  | •                          | •             | •             | •           | •        | •          | •  |
| -                                    | ٠                              | _  | •                          | -             | -             | _           | •        | •          | •  |
| -                                    | •                              | _  | •                          | -             | -             | —           | •        | -          | •  |
| -                                    | •                              | _  | •                          | -             | -             | _           | -        | •          | -  |
| -                                    | ٠                              | _  | •                          | -             | _             | _           | _        | •          | _  |
| -                                    | ٠                              | •  | •                          | Simple ver.   | -             | -           | •        | •          | •  |
| -                                    | ٠                              | •  | •                          | -             | -             | _           | -        | •          | *2   |
| ٠                                    | •                              | •  | •                          | ٠             | -             | -           | •        | •          | •  |
| •                                    | •                              | •  | •                          | -             | -             | —           | -        | •          | -  |
| -                                    | -                              | _  | -                          | _             | -             | —           | _        | -          | -  |
| -                                    | -                              | •  | -                          | -             | -             | _           | -        | •          | -  |
| •                                    | •                              | •  | •                          | •             | •             | •           | •        | •          | •  |
| *1                                   | •                              | •  | •                          | -             | -             | •           | •        | •          | •  |
|                                      | _                              | _  | _                          | -             | _             | _           | _        | -          | _  |
| •                                    | •                              | •  | •                          | •             | •             | •           | •        | •          | •  |
| _                                    | •                              | •  | •                          | -             | _             | _           | _        | •          | _  |
| •                                    | ٠                              | •  | •                          | -             | -             | —           | -        | •          | -  |
| *1                                   | ٠                              | •  | •                          | ٠             | _             | •           | •        | •          | •  |
| •                                    | ٠                              | •  | •                          | •             | -             | •           | •        | •          | •  |
| -                                    | •                              | •  | •                          | _             | _             | —           | _        | •          | _  |
| -                                    | ٠                              | •  | •                          | —             | -             | —           | •        | •          | •  |
| •                                    | ٠                              | •  | •                          | ٠             | ٠             | ٠           | •        | •          | ٠  |
| -                                    | •                              | Simple ver.  | •                          | ٠             | •             | Simple ver. | •        | •          | •  |
| -                                    | ٠                              | •  | •                          | ٠             | -             | ٠           | -        | •          | -  |
| -                                    | ٠                              | -  | •                          | -             | -             | _           | •        | •          | •  |
| -                                    | •                              | -  | •                          | -             | -             | -           | •        | •          | •  |
| -                                    | -                              | -  | -                          | -             | -             | _           | •        | •          | •  |
| -                                    | ٠                              | -  | •                          | _             | _             | _           | _        | •          | _  |
| -                                    | •                              | -  | •                          | _             | -             | -           | -        | -          | -  |
| -                                    | •                              | -  | •                          | _             | -             | _           | •        | •          | •  |
| -                                    | -                              | -  | -                          | -             | -             | -           | -        | -          | -  |
| -                                    | -                              | _  | _                          | _             | _             | _           | _        | -          | _  |

# Solutions

## **MELSERVO Solution**

Introducing the MELSERVO solutions for problems in production sites. We offer the optimal solutions for various problems in various production sites.

### Applications

- Vertical form, fill & seal · Rotary knifes
- Pick and place robots

Converting systems

- Press-fit machines
- Motion alignment (X-Y- θ)
  Convoyor overtome utilizin
  - Conveyor systems utilizing safety observation function
  - Automated guided vehicles · Fly
- Gantry applications
- Eco-friendly conveyors and product handling equipment
  - Flying shears





Screw tightening machines



Exceptional Solutions for All of Your Production Needs Refer to "MELSERVO SOLUTIONS catalog (L(NA)03094)" for details.



## **Function Guide**

Introducing the latest functions for easier and safer operations. MELSERVO-J4 and our servo products come with a wide selection of functions to solve the challenges in production.

- Failure Prediction · Drive Recorder
- Functional Safety · Monitoring
- Master-Slave Operation
- One-Touch Tuning
- Super Trace Control
  Multi-Axis Adjustment

MELCERI/O IA

- Simple Cam
  - Pressure Control
- Refer to "MELSERVO-J4 Function Guide (L(NA)03152ENG)" for details.

Mitsubishi Electric FA Application Package iQ Monozukuri

Offering concentrates on improving the productivity, quality, and concepts for achieving process improvements associated with the construction and configuration of applications, and devices.

- CONVERTING Strongly supporting development of converting systems with unwinder/rewinder control
- HANDLING Strongly supporting development of transportation mechanisms with calculation of coordinate transformation
- PACKAGING Strongly supporting development of packaging machines with cam control and positioning compensation



## e-F@ctory Alliance

The e-F@ctory Alliance is an FA manufacturer partnering program that strongly links the connection compatibility of Mitsubishi Electric FA equipment utilizing excellent software and machinery offered by partners, thereby enabling systems to be built by systems integration partners and the proposal of optimal solutions to customers.



## Mitsubishi Electric Servo System Partners

Servo system includes controllers, servo drivers, actuators, sensors, etc. The servo system takes a step further to accelerate the equipment revolution by collaborating with our partner companies. Now that a wide variety of partner products are available such as pressure-resistance, explosion-proof type motors, custom-made servo motors, magnetic type linear encoders, your system will be configured flexibly. The Mitsubishi Electric Servo System Partner Association is a subcommittee of e-F@ctory Alliance.



proposing excellent application software and drivers that ensure the connection compatibility of Mitsubishi Electric FA

equipment and is easier

# **Production System**

Homes of MELSERVO where the advanced FA technologies are incorporated.

To guarantee the high quality and performance of MELSERVO, Mitsubishi Electric has built a cooperative system of three facilities - Shinshiro Factory, a branch factory of Nagoya Works; MEAMC (Mitsubishi Electric Automation Manufacturing (Changshu) Co., Ltd.) a manufacturing base; and Nagoya Works at the core. Mitsubishi Electric responds to customer needs throughout the world by uniting technologies and know-hows of these facilities.

### Nagoya Works



Integrated manufacturing of servo amplifiers, servo motors, and other Mitsubishi Electric's servo system products.

Nagoya Works was established in 1924 as Mitsubishi Electric's first mass-production factory for electric motors. The lineup of factory automation and mechatronics products has continued to expand gradually since the advent of high economic growth in Japan. Along with its numerous successful achievements, Nagoya Works continues to actively develop solutions for improving productivity and quality.

| Number of employees | 2,500  |
|---------------------|--|
| Site area           | 306,000 m <sup>2</sup>   |
| Gross floor space   | Approx. 252,000 m <sup>2</sup><br>(Satellite factories excluded) |

Shinshiro Factory



Mitsubishi Electric's servo motor manufacturing facility.

Shinshiro Factory was established in 1974 as a satellite factory of Nagoya Works, supplying various types of motors built utilizing the latest mechatronic and system technologies. Moreover, the integrated FA solution e-F@ctory was introduced for the motor shaft processing line, which utilizes many special components. The productivity of the production line has been improved, and the factory is now able to handle multi-model, small-lot production in a shorter period of time.

| Number of employees | 100                    |
|---------------------|------------------------|
| Site area           | 130,000 m <sup>2</sup> |
| Gross floor space   | 42,000 m <sup>2</sup>  |

MEAMC



(Mitsubishi Electric Automation Manufacturing (Changshu) Co., Ltd.)

AC servo manufacturing facility in China

MEAMC was established in June 2011 in Changshu, China, as a manufacturing base. Operations at Factory 2 started in April 2017 in response to the increasing demands for controllers and drive products in China and around the world. FA integrated solution, "e-F@ctory", has been implemented in the manufacturing line to improve productivity and conserve energy.

| Number of employees | 490                   |
|---------------------|-----------------------|
| Site area           | 63,910 m <sup>2</sup> |
| Gross floor space   | 44,810 m <sup>2</sup> |

## Key parts of own manufacturing on unique technology



In the advanced production system integrating the production management system and the FA system based on IT, key components such as power modules and servo-motor encoders for drive control devices and oscillators and lenses for laser machining equipment are manufactured in our company by making the best use of unique technologies. This strategic facility is indispensable for Nagoya Works to enhance competitiveness of its products and to add values to the products.

Passing on technologies developed to future generations



Manufacturing is an achievement of advanced technologies, and at the same time, it is the result of skills passed from person to person. Nagoya Works periodically holds Nagoya Works Technology School, in which educational sessions are conducted where senior engineers teach younger engineers techniques and procedures such as machining, finishing, welding, and assembly of electronic components. The skills developed are passed on to future generations as precious resources of manufacturing.

Painstaking quality assurance through the application of cutting-edge testing equipment.



Ultrasonic Probing Devices



X-ray scanners



EMC chamber (large-size anechoic chamber)



LSI testers



Equipment for highly accelerated limit test (HALT)

# R&D

World-class R&D capabilities to offer a unique set of servo systems.

To bring cutting-edge servo systems to worldwide market, Mitsubishi Electric has established FA-related development centers in its Nagoya Works, Europe, the U.S., and India.

Together with our Advanced Technology R&D Center, and Information and Technology R&D Center, we are moving forward with the development of new products to correspond to technology trends and the voices of our customers.

## Japan (Nagoya Works)

FA Development Center



Integrating product-development ability as a comprehensive FA supplier

The FA Development Center is comprised of engineers who specialized in controllers and drive system products. Its function is to promote higher product compatibility and integration, as well as improve the overall performance of Mitsubishi Electric FA products by merging the respective technologies of different parties at a high level. The newly added Experiment and Verification Room is used for joint development projects with customers and development partners. The Center has a secure Internet environment, and the connection status of our FA devices and software can be assessed easily. This shortens the development timeframe and enables us to be one step ahead in creating FA products that connect to the world and meet the needs of the IoT era.

In addition, the number of prototypes necessary in the product planning, development, design and prototype phases has been reduced through simulation technology built in a virtual environment. The product development timeframe has also been shortened and design quality improved by reducing the man-hours required for evaluation.

### Mechatronics Development Center



Advanced base for advantage of technology and development of industrial mechatronics products

In addition to FA devices, industrial mechatronics products are another major product line manufactured at Nagoya Works. The Mechatronics Development Center is the development base for these products. It has established advanced machining technologies that enable highly accurate ultrafine machining at the nanometer-level, and works to improve development efficiency and reduce development time by seamlessly linking itself with relevant technological organizations. It is also utilized for joint development projects with our customers, leading to the creation of products that can be used, and new applications and new markets.

## Japan (Mitsubishi Electric R&D)

Advanced Technology R&D Center



The Advanced Technology R&D Center engages in next-generation product development utilizing the fundamental technologies that underpin our business and R&D, which helps to sow the seeds for new business in the future and aims to create new values accepted by society.

## Information and Technology R&D Center



As the main base for information and communication technology development, the Information and Technology R&D Center conducts R&D in the fields of information, multimedia, optic radio waves and communication technologies and solution proposal-type development utilizing IT.

## **Global Development Centers**

Global development centers and Mitsubishi Electric domestic laboratories collaborating to lead the world in product development

European Development Center (EDC)





North American Development

Center (NADC)

India Development Center (INDC)



China Development Center (CDC)



Passing our technologies and experiences from one generation to the next, Mitsubishi Electric continuously strives for cutting-edge technology.



In 1987, Mitsubishi Electric announced MELSERVO-SA, the first completely digital hardware logic product at a time when analog products were at their zenith. Since then, we have pioneered servo technology in Japan. Carrying that heritage forward, we will continuously offer you globally-acknowledged servo systems that completely satisfy your needs.

